# Uniformizing model of type $\boldsymbol{A}_{3}$ and almost Belyi functions 

Jiro SEKIGUCHI


#### Abstract

We first review the result by K. Saito on the uniformization of the discriminant loci for the case of the root system of type $A_{3}$. Then we formulate a generalization of his result and construct three examples which satisfy the uniformizing model after K. Saito.


## 1. Introduction

The discriminant $\Delta\left(A_{3}\right)$ of the polynomial $f(t)=t^{4}+x_{1} t^{2}+x_{2} t+x_{3}$ has many interesting properties. Among others we focus our attention on the relation

$$
-\frac{1}{108} \Delta\left(A_{3}\right)=L_{0}(x)^{3}+M_{0}(x)^{2},
$$

where $L_{0}, M_{0}$ are polynomials (cf. (2), (3) in the main text). K. Saito ([3]) constructed a uniformization of the complement of $\Delta\left(A_{3}\right)=0$ of $\mathbf{C}^{3}$ with the help of this relation. Noting that $\Delta\left(A_{3}\right)=0$ is also a free divisor, we are led to ask the question whether there is a polynomial of three variables which defines a free divisor and has a kind of the relation similar to (3). If there is a polynomial satisfying these two conditions, it is expected to develop an argument analogues to [3]. The author treated a generalization to the following case, namely, the case where there exists a triplet of functions $\{F, L, M\}$ of three variables satisfying
(A1) $F, L, M$ are polynomials of $\left(x_{1}, x_{2}, x_{3}\right)$.
(A2) $F=0$ is a free divisor in the sense of [4].
(A3:p) $F=L^{p}+M^{2}$ for some positive integer $p$.
See [6], [7] for details. It is underlined here that if $p=3$, it is hard to find the triplet $\{F, L, M\}$ satisfying (A1), (A2), (A3:3) except the case of the discriminant $\Delta\left(A_{3}\right)$ treated by K. Saito.

In this paper we discuss a generalization of the above Saito's result in another direction. Namely we discuss the possibility of the existence of a triplet $\{F, L, M\}$ of three variables when Condition (A1) is changed to (A1)' below while keeping Conditions (A2), (A3:p):

[^0](A1)' $F$ is a polynomial but both $L, M$ are algebraic functions of $\left(x_{1}, x_{2}, x_{3}\right)$.
If there is a triplet $\{F, L, M\}$ with Conditions (A1)', (A2), (A3:p), it is possible to develop the argument in $\{F, L, M\}$ similar to that in the case of the discriminant of type $A_{3}$ (cf. [3]).

Among others, it is one of basic problems to construct such triplets $\{F, L, M\}$ with Conditions (A1)', (A2), (A3:p). The idea to perform this purpose employed in this paper is the use of a generalization of Belyi functions, that is, the so called "almost Belyi functions" introduced by A. V. Kitaev [2]. Then it is possible to construct examples of the triplets at least in the case $p=3$. We explain the reason why the research on the almost Belyi function can be applied to the construction of the triplet $\{F, L, M\}$ with Conditions (A1)', (A2), (A3:3) briefly. Some of almost Belyi functions are realized in the following manner.

There are four weighted homogeneous polynomials $h_{1}, h_{2}, h_{3}, h_{4}$ of three variables $x_{1}, x_{2}, x_{3}$ with Conditions (E1), (E2):
(E1) $h_{2}=0$ defines a free divisor in $\mathbf{C}^{3}$.
(E2) $h_{1}^{5} h_{2}=h_{3}^{3}+h_{4}^{2}$.
Then $Z=\frac{h_{1}^{5} h_{2}}{h_{3}^{3}}$ is an almost Belyi function introduced by A. Kitaev.
We now focus our attention on Condition (E2). By putting $F=h_{2}, L=\frac{h_{3}}{h_{1}^{5 / 3}}, M=\frac{h_{4}}{h_{1}^{5 / 2}}$, we obtain the relation given in (A3:3).

This observation suggests that some of almost Belyi functions provide triplets $\{F, L, M\}$ with Conditions (A1)', (A2), (A3:3). Then it is worth checking to apply the arguments in the case of the discriminant $\Delta\left(A_{3}\right)$ to such triplets $\{F, L, M\}$ constructed by the use of almost Belyi functions. The motivation of the present study is to see if this attempt leads to a good conclusion or not. The purpose of this paper is to construct examples of the triplet $\{F, L, M\}$ and study some properties of them. In spite that the result obtained is not satisfactory, the author hopes the efforts developed in this paper will be useful for researches on free divisors, almost Belyi functions and the uniformization.

The construction of this paper is as follows. In section 2, we review the result by K. Saito [3] and in section 3, we will formulate the notion of the uniformizing model of type $A_{3}$ and confirm the argument for the discriminant of type $A_{3}$ hold for the case of the uniformizing model of type $A_{3}$. The definition of the almost Belyi function and its interpretation in terms of the use of free divisors are explained in section 4. In section 5 , we will construct three examples of the triplets $\{F, L, M\}$ by using almost Belyi functions. The first example is related with the free divisor defined by the polynomial $F_{B, 6}$ found in [5] and the almost Belyi function
introduced in [9]. The second example is related with the discriminant of the real reflection group of type $H_{3}$. The third example is related with the almost Belyi function found by Kitaev [2].

## 2. The case of $A_{3}$. A prototype

We give a survey on the result of [3] in this section.
The discriminant $\Delta\left(A_{3}\right)$ of the polynomial of $t$ defined by $f(t)=t^{4}+x_{1} t^{2}+$ $x_{2} t+x_{3}$ coincides with the determinant of the matrix

$$
M_{\Delta\left(A_{3}\right)}=\left(\begin{array}{ccc}
2 x_{1} & 3 x_{2} & 4 x_{3} \\
3 x_{2}-x_{1}^{2}+4 x_{3} & -\frac{1}{2} x_{1} x_{2} \\
4 x_{3} & -\frac{1}{2} x_{1} x_{2} & \frac{1}{4}\left(-3 x_{2}^{2}+8 x_{1} x_{3}\right)
\end{array}\right)
$$

up to a constant factor. It is easy to see that $\Delta\left(A_{3}\right)$ defines a free divisor. This is shown as follows. Let $V_{1}, V_{2}, V_{3}$ be vector fields defined by

$$
{ }^{t}\left(V_{1}, V_{2}, V_{3}\right)=M_{\Delta\left(A_{3}\right)}{ }^{t}\left(\partial_{x_{1}}, \partial_{x_{2}}, \partial_{x_{3}}\right) .
$$

Then by direct computation, we have

$$
V_{1} \Delta\left(A_{3}\right)=12 \Delta\left(A_{3}\right), \quad V_{2} \Delta\left(A_{3}\right)=0, \quad V_{3} \Delta\left(A_{3}\right)=2 x_{1} \Delta\left(A_{3}\right) .
$$

and these imply that $\Delta\left(A_{3}\right)=0$ is free.
The system of differential equations

$$
\left\{\begin{array}{l}
V_{1} u=-u,  \tag{1}\\
V_{2} V_{2} u=0, \\
V_{2} V_{3} u=-\frac{1}{2} x_{2} u-\frac{1}{2} x_{1} V_{2} u, \\
V_{3} V_{3} u=-x_{3} u-\frac{x_{2}}{4} V_{2} u
\end{array}\right.
$$

is introduced in [3]. This is an example of uniformizing systems of equations singular along $\Delta\left(A_{3}\right)=0$. We will construct solutions of (1) following the idea by K . Saito. We first introduce polynomials

$$
\begin{equation*}
L_{0}(x)=-\frac{1}{9}\left(12 x_{3}+x_{1}^{2}\right), \quad M_{0}(x)=\frac{1}{54}\left(2 x_{1}^{3}+27 x_{2}^{2}-72 x_{1} x_{3}\right) . \tag{2}
\end{equation*}
$$

It is easy to see that

$$
\begin{equation*}
-\frac{1}{108} \Delta\left(A_{3}\right)=L_{0}(x)^{3}+M_{0}(x)^{2}, \tag{3}
\end{equation*}
$$

(4) $V_{1} L_{0}=4 L_{0}, V_{1} M_{0}=6 M_{0}, V_{2} L_{0}=V_{2} M_{0}=0, V_{3}^{\prime} L_{0}=M_{0}, V_{3}^{\prime} M_{0}=-\frac{3}{2} L_{0}^{2}$.

Here we put

$$
V_{3}^{\prime}=\frac{1}{2}\left(V_{3}-\frac{1}{6} x_{1} V_{1}\right)
$$

Let

$$
\begin{equation*}
P(t)=t^{3}+3 L_{0}(x) t+2 M_{0}(x) \tag{5}
\end{equation*}
$$

be a cubic polynomial of $t$. Then the following formulas are easy to show:

$$
\begin{align*}
P\left(-\frac{2}{3} x_{1}\right) & =x_{2}^{2}  \tag{6}\\
\left(V_{1}+2 t \partial_{t}\right) P & =6 P
\end{align*}
$$

(7)

$$
\begin{aligned}
& \left(V_{3}^{\prime 2}-\frac{1}{16} L_{0}(x)\right) P(t)^{-1 / 2} \\
= & \frac{1}{8} \frac{\partial}{\partial t}\left\{\left(L_{0}(x) t^{4}-3 L_{0}(x)^{2} t^{2}-4 L_{0}(x) M_{0}(x) t-12\left(M_{0}(x)^{2}+L_{0}(x)^{3}\right)\right) P(t)^{-3 / 2}\right\} .
\end{aligned}
$$

We put

$$
\begin{equation*}
\eta(x)=\frac{1}{2} \int_{\infty}^{\varphi(x)} P(t)^{-1 / 2} d t \tag{8}
\end{equation*}
$$

where $\varphi(x)=-\frac{2}{3} x_{1}$. Since $P(\varphi)=x_{2}^{2}$, we take the branch of $P(t)^{1 / 2}$ so that $P(\varphi)^{1 / 2}=x_{2}$. Then, by an argument explained in [3], we see that

$$
V_{1} \eta=-\eta, \quad V_{2} \eta=-1
$$

To compute $V_{3}^{\prime 2} \eta$, we first note that

$$
V_{3}^{\prime} \eta=\frac{1}{2} \int_{\infty}^{\varphi} V_{3}^{\prime}\left(P^{-1 / 2}\right) d t+\frac{\left(V_{3}^{\prime} \varphi\right)}{2 x_{2}}
$$

and

$$
V_{3}^{\prime 2} \eta=\frac{1}{2}\left\{\int_{\infty}^{\varphi} V_{3}^{\prime 2}\left(P^{-1 / 2}\right) d t+\left.\left(V_{3}^{\prime} P(t)^{-1 / 2}\right)\right|_{t=\varphi} \cdot\left(V_{3}^{\prime} \varphi\right)+V_{3}^{\prime}\left(\frac{\left(V_{3}^{\prime} \varphi\right)}{x_{2}}\right)\right\}
$$

Then

$$
\begin{aligned}
& \left(V_{3}^{\prime 2}-\frac{1}{16} L_{0}\right) \eta \\
= & \frac{1}{2}\left\{\int_{\infty}^{\varphi}\left(V_{3}^{\prime 2}-\frac{1}{16} L_{0}\right) P(t)^{-1 / 2} d t+\left.\left(V_{3}^{\prime} P(t)^{-1 / 2}\right)\right|_{t=\varphi} \cdot\left(V_{3}^{\prime} \varphi\right)+V_{3}^{\prime}\left(\frac{\left(V_{3}^{\prime} \varphi\right)}{x_{2}}\right)\right\} \\
= & \left.\frac{1}{16}\left\{\left(L_{0}(x) t^{4}-3 L_{0}(x)^{2} t^{2}-4 L_{0}(x) M_{0}(x) t-12\left(M_{0}(x)^{2}+L_{0}(x)^{3}\right)\right)\right) P(t)^{-3 / 2}\right\}\left.\right|_{t=\varphi} \\
& +\frac{1}{2}\left\{\left.\left(V_{3}^{\prime} P(\varphi)^{-1 / 2}\right)\right|_{t=\varphi} \cdot\left(V_{3}^{\prime} \varphi\right)+V_{3}^{\prime}\left(\frac{\left(V_{3}^{\prime} \varphi\right)}{x_{2}}\right)\right\} \\
= & \frac{1}{16 x_{2}^{3}}\left(L_{0}(x) \varphi^{4}-3 L_{0}(x)^{2} \varphi^{2}-4 L_{0}(x) M_{0}(x) \varphi-12\left(M_{0}(x)^{2}+L_{0}(x)^{3}\right)\right) \\
& +\frac{1}{2}\left\{\left.\left(V_{3}^{\prime} P(t)^{-1 / 2}\right)\right|_{t=\varphi} \cdot\left(V_{3}^{\prime} \varphi\right)+V_{3}^{\prime}\left(\frac{\left(V_{3}^{\prime} \varphi\right)}{x_{2}}\right)\right\} .
\end{aligned}
$$

It follows from direct computation that

$$
\begin{aligned}
V_{3}^{\prime} \varphi & =\frac{1}{2} \varphi^{2}+L_{0} \\
V_{3}^{\prime 2} \varphi & =\frac{1}{2} \varphi^{3}+L_{0} \varphi+M_{0} \\
V_{3}^{\prime} x_{2} & =\frac{3}{4} \varphi x_{2} \\
V_{3}^{\prime} P(t) & =3\left(M_{0} t-L_{0}^{2}\right)
\end{aligned}
$$

As a consequence, we have

$$
\left.V_{3}^{\prime} P(t)^{-1 / 2}\right|_{t=\varphi}=-\frac{3\left(M_{0} \varphi-L_{0}^{2}\right)}{2 x_{2}^{3}}, \quad V_{3}^{\prime}\left(\frac{V_{3}^{\prime} \varphi}{x_{2}}\right)=\frac{\varphi^{3}+2 L_{0} \varphi+8 M_{0}}{8 x_{2}}
$$

Then

$$
\begin{aligned}
& \frac{1}{16 x_{2}^{3}}\left(L_{0}(x) \varphi^{4}-3 L_{0}(x)^{2} \varphi^{2}-4 L_{0}(x) M_{0}(x) \varphi-12\left(M_{0}(x)^{2}+L_{0}(x)^{3}\right)\right) \\
&+\left.\frac{1}{2}\left(V_{3}^{\prime} P(t)^{-1 / 2}\right)\right|_{t=\varphi} \cdot\left(V_{3}^{\prime} \varphi\right) \\
&= \frac{L_{0}(x) \varphi^{4}-3 L_{0}(x)^{2} \varphi^{2}-4 L_{0}(x) M_{0}(x) \varphi-12\left(M_{0}(x)^{2}+L_{0}(x)^{3}\right)}{16 x_{2}^{3}} \\
&-\frac{3\left(M_{0} \varphi-L_{0}^{2}\right)\left(\varphi^{2}+2 L_{0}\right)}{8 x_{2}^{3}} \\
&= \frac{1}{16 x_{2}^{3}}\left\{L_{0}(x) \varphi^{4}-3 L_{0}(x)^{2} \varphi^{2}-4 L_{0}(x) M_{0}(x) \varphi-12\left(M_{0}(x)^{2}+L_{0}(x)^{3}\right)\right. \\
&\left.\quad-6\left(M_{0} \varphi-L_{0}^{2}\right)\left(\varphi^{2}+2 L_{0}\right)\right\}
\end{aligned}
$$

$$
\begin{aligned}
& =\frac{P(\varphi)\left(L_{0} \varphi-6 M_{0}\right)}{16 x_{2}^{3}} \\
& =\frac{L_{0} \varphi-6 M_{0}}{16 x_{2}},
\end{aligned}
$$

which implies

$$
\begin{aligned}
& \frac{L_{0}(x) \varphi^{4}-3 L_{0}(x)^{2} \varphi^{2}-4 L_{0}(x) M_{0}(x) \varphi-12\left(M_{0}(x)^{2}+L_{0}(x)^{3}\right)}{16 x_{2}^{3}} \\
& +\frac{1}{2}\left\{\left.\left(V_{3}^{\prime} P(t)^{-1 / 2}\right)\right|_{t=\varphi} \cdot\left(V_{3}^{\prime} \varphi\right)+V_{3}^{\prime}\left(\frac{\left(V_{3}^{\prime} \varphi\right)}{x_{2}}\right)\right\} \\
= & \frac{x_{2}}{16} .
\end{aligned}
$$

Therefore we obtain

$$
\left(V_{3}^{\prime 2}-\frac{L_{0}}{16}\right) \eta=\frac{x_{2}}{16} .
$$

Since $V_{2} \eta=-1$, we find that

$$
V_{3}^{\prime 2} \eta=-\frac{1}{16} x_{2} V_{2} \eta+\frac{1}{16} L_{0}(x) \eta .
$$

As a consequence, it follows that the function $\eta(x)$ is a solution of

$$
\left\{\begin{array}{l}
V_{1} u=-u  \tag{9}\\
V_{2}^{2} u=0 \\
V_{3}^{\prime} V_{2} u=0 \\
V_{3}^{\prime 2} u=-\frac{1}{16} x_{2} V_{2} u+\frac{1}{16} L_{0}(x) u
\end{array}\right.
$$

It is easy to show that (1) is same as (9).
If $u(x)$ is a solution of (9) such that $V_{2} u=0$, then $u$ is a solution of the system

$$
\begin{equation*}
V_{1} u=-u, V_{2} u=0, V_{3}^{\prime 2} u=\frac{1}{16} L_{0} u \tag{10}
\end{equation*}
$$

One method to solve this system is to reduce it to Gaussian hypergeometric differential equation. In fact, putting $x=\frac{L_{0}^{3}+M_{0}^{2}}{L_{0}^{3}}$ and $u=L_{0}^{-1 / 4} f(x)$, we obtain

$$
\left(V_{3}^{\prime 2}-\frac{L_{0}}{16}\right) u=9 L_{0}^{3 / 4}\left\{x\left(\vartheta+\frac{1}{12}\right)\left(\vartheta+\frac{5}{12}\right)-\vartheta^{2}\right\} f(x),
$$

where $\vartheta=x \frac{d}{d x}$. As a consequence, we find that $u=L_{0}^{-1 / 4} F\left(\frac{1}{12}, \frac{5}{12}, 1 ; x\right)$ is a solution to (10). In this manner, we obtain three linearly independent solutions of (1).

The equation $P\left(-\frac{2}{3} x_{1}\right)=x_{2}^{2}$ is equivalent to

$$
\begin{equation*}
Y^{2}=4 X^{3}-g_{2} X-g_{3} \tag{11}
\end{equation*}
$$

under the correspondence

$$
X=-\frac{2}{3} x_{1}, Y=2 x_{2}, g_{2}=-12 L_{0}, g_{3}=-8 M_{0} .
$$

Noting this and taking appropriate linearly independent solutions $u_{1}, u_{2}$ of (10) which are expressed by hypergeometric functions, we define a map

$$
\left(x_{1}, x_{2}, x_{3}\right) \rightarrow\left(u_{1}(x), u_{2}(x), \eta(x)\right)
$$

which is defined on the universal covering $\mathcal{U}$ of $\mathbf{C}^{3}-\{\Delta=0\}$ and its image domain coincides with

$$
\mathcal{S}=\left\{\left(u_{1}, u_{2}, \eta\right): \operatorname{Im}\left(u_{1} / u_{2}\right)>0, m u_{1}+n u_{2} \neq \eta(\forall m, n \in \mathbf{Z})\right\} .
$$

By the theory of elliptic functions, the inversion map for $\left(u_{1}, u_{2}, \eta\right): \mathcal{U} \rightarrow \mathcal{S}$ is realized by

$$
\left\{\begin{align*}
-\frac{2}{3} x_{1} & =\wp\left(\eta, u_{1}, u_{2}\right)=\frac{1}{\eta^{2}}+\sum^{\prime}\left\{\frac{1}{\left(\eta-m u_{1}-n u_{2}\right)^{2}}-\frac{1}{\left(m u_{1}+n u_{2}\right)^{2}}\right\}  \tag{12}\\
2 x_{2} & =\wp^{\prime}\left(\eta, u_{1}, u_{2}\right)=-2\left\{\frac{1}{\eta^{3}}+\sum^{\prime} \frac{1}{\left(\eta-m u_{1}-n u_{2}\right)^{3}}\right\} \\
-12 L_{0} & =\frac{4}{3}\left(12 x_{3}+x_{1}^{2}\right)=60 \sum^{\prime} \frac{1}{\left(m u_{1}+n u_{2}\right)^{4}} .
\end{align*}\right.
$$

## 3. Uniformizing models of type $\boldsymbol{A}_{3}$

In this section, we formulate an analogue of the result explained in the previous section.

First we take a weighted homogeneous polynomial $F\left(x_{1}, x_{2}, x_{3}\right)$ of three variables with weights $w\left(x_{j}\right)=d_{j}(j=1,2,3)$ such that $d_{1}, d_{2}, d_{3}$ are positive integers and assume that $d_{1} \leq d_{2} \leq d_{3}$. Then $E=d_{1} x_{1} \partial_{x_{1}}+d_{2} x_{2} \partial_{x_{2}}+d_{3} x_{3} \partial_{x_{3}}$ is a vector field such that $E F=k_{0} F$ for some positive integer $k_{0}$.

We assume that there are functions $L=L\left(x_{1}, x_{2}, x_{3}\right), \varphi=\varphi\left(x_{1}, x_{2}, x_{3}\right), \tau=$ $\tau\left(x_{1}, x_{2}, x_{3}\right)$, vector fields $V, W$ on $\mathbf{C}^{3}$ and a positive number $k_{1}$ with the following conditions:
(B1) $E L=4 k_{1} L, E \varphi=2 k_{1} \varphi, E \tau=3 k_{1},[E, W]=k_{1} W,[E, V]=2 k_{1} V$,
(B2) $\operatorname{det}\left(\frac{\partial(\varphi, \tau, L)}{\partial\left(x_{1}, x_{2}, x_{3}\right)}\right)$ is not identically zero,
(B3) $4 L^{3}+\left(\tau^{2}-\varphi^{3}-3 L \varphi\right)^{2}=c_{0} F$ for some non-zero number $c_{0}$.
(B4) $V \varphi=\frac{1}{2} \varphi^{2}+L, V \tau=\frac{3}{4} \varphi \tau, V L=\frac{1}{2}\left(\tau^{2}-\varphi^{3}-3 L \varphi\right)$,
(B5) $W \varphi=\tau, W \tau=\frac{3}{2}\left(\varphi^{2}+L\right), W L=0$.
Definition 3.1. A uniformizing model of type $A_{3}$ is the data $\{F, L, M, E, V, W, \varphi, \tau\}$ consisting of a polynomial $F=F\left(x_{1}, x_{2}, x_{3}\right)$, functions $L, M, \varphi, \tau$, vector fields $E, W, V$ with the conditions (B1)-(B5).

As easy consequences of Conditions (B1)-(B5), we have the following.
(C1) Put $M=\frac{1}{2}\left(\tau^{2}-\varphi^{3}-3 L \varphi\right)$ and $P(t)=t^{3}+3 L t+2 M$. Then $P(\varphi)=\tau^{2}$ and the discriminant of $P(t)$ coincides with $L^{3}+M^{2}$ up to a constant factor.
(C2) $V L=M, V M=-\frac{3}{2} L, W M=0, L^{3}+M^{2}=\frac{c_{4}}{4} F$.
(C3) $\left(V^{2}-\frac{1}{16}\right) P(t)^{-1 / 2}=\frac{1}{8} \frac{\partial}{\partial t}\left\{\left(L t^{4}-3 L t^{2}-4 L M t-12\left(L^{3}+M^{2}\right)\right) P(t)^{-3 / 2}\right\}$.
(C4) We define vector fields $E^{*}, W^{*}, V^{*}$ on the $(\varphi, \tau, L)$-space by

$$
\begin{aligned}
& E^{*}=2 \varphi \partial_{\varphi}+3 \tau \partial_{\tau}+4 L \partial_{L}, \\
& W^{*}=\tau \partial_{\varphi}+\frac{3}{2}\left(\varphi^{2}+L\right) \partial_{\tau}, \\
& V^{*}=\left(\frac{1}{2} \varphi^{2}+L\right) \partial_{\varphi}+\frac{3}{4} \varphi \tau \partial_{\tau}+\frac{1}{2}\left(\tau^{2}-\varphi^{3}-3 L \varphi\right) \partial_{L} .
\end{aligned}
$$

Then there is a natural correspondence

$$
(E, W, V) \longleftrightarrow\left(k_{1} E^{*}, W^{*}, V^{*}\right)
$$

and $4 L^{3}+\left(\tau^{2}-\varphi^{3}-3 L \varphi\right)^{2}$ defines a free divisor on the $(\varphi, \tau, L)$-space and $E^{*}, W^{*}, V^{*}$ generate the Lie algebra of the logarithmic vector fields along the free divisor $4 L^{3}+\left(\tau^{2}-\varphi^{3}-3 L \varphi\right)^{2}=0$.

Remark 3.2. An identification between the variables $x_{1}, x_{2}, x_{3}$ of §2 and $\varphi, \tau, L$ is given by $\varphi=-\frac{2}{3} x_{1}, \tau=x_{2}, L=-\frac{1}{9}\left(12 x_{3}+x_{1}^{2}\right)$.

Noting the property (C4), we define a system of differential equations

$$
\left\{\begin{array}{l}
E u=-k_{1} u  \tag{13}\\
W^{2} u=0 \\
V W u=0 \\
V^{2} u=\left(\frac{L}{16}+\frac{\tau}{8} W\right) u
\end{array}\right.
$$

This system is an analogue to (9). This observation suggests that solutions to (13) can be constructed by an argument similar to that developed in the previous section, which we are going to do. We first introduce a function $\eta(x)$ of $x=$ $\left(x_{1}, x_{2}, x_{3}\right)$ defined by

$$
\eta(x)=\frac{1}{2} \int_{\infty}^{\varphi} P(t)^{-1 / 2} d t
$$

For a moment, we take a branch of $P(t)$ such that $P(\varphi)^{1 / 2}=\tau$. It is clear from the definition that $E \eta=-k_{1} \eta$. On the other hand, (B5) shows that $W \eta=\frac{1}{2}$. This implies that $W^{2} \eta=V W \eta=0$. Moreover using (B1)-(B5), we find that $V^{2} \eta=\frac{1}{16} L \eta+\frac{\tau}{16}$. This combined with $W \eta=1 / 2$ implies that $V^{2} \eta=\left(\frac{L}{16}+\frac{\tau}{16} W\right) \eta$. As a consequence, $\eta(x)$ is a solution to (13).

It is clear that the argument of the previous section shows

$$
\left\{\begin{align*}
\varphi & =\wp\left(\eta, u_{1}, u_{2}\right)  \tag{14}\\
& =\frac{1}{\eta^{2}}+\sum^{\prime}\left\{\frac{1}{\left(\eta-m u_{1}-n u_{2}\right)^{2}}-\frac{1}{\left(m u_{1}+n u_{2}\right)^{2}}\right\} \\
2 \tau \quad & =\wp^{\prime}\left(\eta, u_{1}, u_{2}\right)\left(=-2\left\{\frac{1}{\eta^{3}}+\sum^{\prime} \frac{1}{\left(\eta-m u_{1}-n u_{2}\right)^{3}}\right\}\right) \\
-12 L & =60 \sum^{\prime} \frac{1}{\left(m u_{1}+n u_{2}\right)^{4}}
\end{align*}\right.
$$

It is non-trivial to write down $x_{1}, x_{2}, x_{3}$ by $\varphi, \tau, L$.
We propose a few basic problems on the uniformizing model of type $A_{3}$.
(D1) Find the uniformizing models of type $A_{3}$.
(D2) Solve the system of equations (14) for $x_{1}, x_{2}, x_{3}$.
(D3) Classify the uniformizing models of type $A_{3}$.
Remark 3.3. In this paper, the problems (D1) and (D2) are treated but (D3)
is not.

## 4. Almost Belyi functions

An almost Belyi function introduced by Kitaev [2] is an algebraic covering $\varphi$ : $C \longrightarrow \mathbf{P}^{1}$ that branches above $\{0,1, \infty\}$ of $\mathbf{P}^{1}$ and has exactly one simple branching point outside the fibres $\{0,1, \infty\}$ of $\mathbf{P}^{1}$. One of the reasons why Kitaev introduced almost Belyi functions is to construct algebraic solutions to Painlevé VI equation with the help of almost Belyi functions (cf. [2]). There is a deep relationship between some of almost Belyi functions and free divisors in three variables. We explain a typical case of such almost Belyi functions. See [8] for the interpretation of the almost Belyi functions in terms of free divisors. There are four weighted homogeneous polynomials $h_{1}, h_{2}, h_{3}, h_{4}$ of $x_{1}, x_{2}, x_{3}$ with the following conditions.
(E1) $h_{2}=0$ is a free divisor in $\mathbf{C}^{3}$,
(E2) $h_{1}^{5} h_{2}=h_{3}^{3}+h_{4}^{2}$.
Then (E2) implies that $Z=\frac{h_{1}^{5} h_{2}}{h_{3}^{3}}$ defines an almost Belyi function. We focus our attention on the equation of (E2), which is equivalent to

$$
\begin{equation*}
h_{2}=\frac{h_{3}^{3}}{h_{1}^{5}}+\frac{h_{4}^{2}}{h_{1}^{5}} . \tag{15}
\end{equation*}
$$

There is a similarity between the last equation of the property (C2) and (15) by putting

$$
L=\frac{h_{3}}{h_{1}^{5 / 3}}, \quad M=\frac{h_{4}}{h_{1}^{5 / 2}} .
$$

This suggests the possibility of constructing examples of uniformizing models of type $A_{3}$ with the help of almost Belyi functions. It is underlined here that $L$ and $M$ are not polynomials but algebraic functions of $x_{1}, x_{2}, x_{3}$. Even assuming Conditions (E1), (E2), we need to show the existence of the functions $\varphi$ and $\tau$ to reach the goal. Therefore we focus our efforts on the discovery of $\varphi, \tau$ in each case of almost Belyi functions. The meaning of $\varphi, \tau$ is left to future research.

## 5. Examples of uniformizing models of type $\boldsymbol{A}_{3}$

In this section, we focus our attention on the construction problem of uniformizing model of type $A_{3}$. We treat three examples of uniformizing models of type $A_{3}$ which are constructed with the help of almost Belyi functions. In the first exam-
ple, the problems (D1), (D2) explained in §3 are solved. In the second and third examples, (D1) is solved but (D2) is still open.

### 5.1. Example 1: Free divisor defined by $\boldsymbol{F}_{B, 6}$

We start with the $3 \times 3$ matrix

$$
M_{B, 6}=\left(\begin{array}{ccc}
x_{1} & 2 x_{2} & 3 x_{3} \\
-\frac{4}{15}\left(5 x_{1}^{2}-3 x_{2}\right) & \frac{1}{15}\left(-4 x_{1} x_{2}+15 x_{3}\right) & \frac{2}{5}\left(9 x_{2}^{2}+5 x_{1} x_{3}\right) \\
\frac{1}{15}\binom{10 x_{1}^{3}-56 x_{1} x_{2}}{+15 x_{3}} & \frac{1}{30} x_{2}\left(4 x_{1}^{2}+25 x_{2}\right) & \frac{1}{5}\binom{-9 x_{1} x_{2}^{2}-5 x_{1}^{2} x_{3}}{+10 x_{2} x_{3}}
\end{array}\right) .
$$

The polynomial $f_{0}=\operatorname{det}\left(M_{B, 6}\right)$ defines a free divisor same as $F_{B, 6}$ introduced in [5]. Let $V_{1}, V_{2}, V_{3}$ be vector fields by using $M_{B, 6}$ similar to the case of $A_{3}$. In this case, it is easy to show that

$$
V_{1} f_{0}=9 f_{0}, \quad V_{2} f_{0}=0, \quad V_{3} f_{0}=0
$$

There is an almost Belyi function related with the polynomial $f_{0}$ which we are going to introduce. Let $F_{8}, G_{8}, P_{8}$ be the polynomials of $x, s$ defined in [9, p.8], namely

$$
\begin{aligned}
& F_{8}=9(s+1)^{2} x^{3}-24 s(s+3) x^{2}+8 s(11 s-1) x+48 s^{2}, \\
& G_{8}=x^{2}-2 s x-s, \\
& P_{8}=3(s+1)^{2} x^{4}-4 s(s+3) x^{3}+12 s(s-1) x^{2}+24 s^{2} x+8 s^{2} .
\end{aligned}
$$

We also define (cf. [9])

$$
\varphi_{8}(x, s)=\frac{(s+1)^{2} x^{5} F_{8}}{64 s G_{8}^{3}} .
$$

Then

$$
\varphi_{8}(x, s)-1=\frac{P_{8}^{2}}{64 s G_{8}^{3}}
$$

which is equivalent to the identity

$$
\begin{equation*}
(s+1)^{2} x^{5} F_{8}-64 s G_{8}^{3}-P_{8}^{2}=0 \tag{16}
\end{equation*}
$$

To connect $F_{8}, G_{8}, P_{8}$ with the polynomial $f_{0}$, we introduce rational functions $\tilde{x}, \tilde{s}$
of $x_{1}, x_{2}, x_{3}$ by

$$
\tilde{x}=\frac{x_{1} x_{3}}{3 x_{2}^{2}}, \quad \tilde{s}=\frac{-x_{1}^{2}}{x_{1}^{2}-4 x_{2}}
$$

and polynomials $h_{1}, h_{2}, h_{3}, h_{4}$ by

$$
\begin{aligned}
& h_{1}=x_{3}, \\
& h_{2}=9 x_{1} x_{2}^{4}+6 x_{1}^{2} x_{2}^{2} x_{3}-2 x_{2}^{3} x_{3}+x_{1}^{3} x_{3}^{2}-6 x_{1} x_{2} x_{3}^{2}+x_{3}^{3}, \\
& h_{3}=9 x_{2}^{4}+6 x_{1} x_{2}^{2} x_{3}+x_{1}^{2} x_{3}^{2}-4 x_{2} x_{3}^{2}, \\
& h_{4}=27 x_{2}^{6}+27 x_{1} x_{2}^{4} x_{3}+9 x_{1}^{2} x_{2}^{2} x_{3}^{2}-18 x_{2}^{3} x_{3}^{2}+x_{1}^{3} x_{3}^{3}-6 x_{1} x_{2} x_{3}^{3}+2 x_{3}^{4} .
\end{aligned}
$$

Then it is straightforward to show that

$$
\begin{aligned}
& F_{8}(\tilde{x}, \tilde{s})=\frac{16 x_{1}^{3} h_{2}}{3\left(x_{1}^{2}-4 x_{2}\right)^{2} x_{2}^{4}}, \\
& G_{8}(\tilde{x}, \tilde{s})=\frac{x_{1}^{2} h_{3}}{9\left(x_{1}^{2}-4 x_{2}\right) x_{2}^{4}}, \\
& P_{8}(\tilde{x}, \tilde{s})=\frac{8 x_{1}^{4} h_{4}}{27\left(x_{1}^{2}-4 x_{2}\right)^{2} x_{2}^{6}} .
\end{aligned}
$$

We note that $f_{0}=-3 h_{2}$. Moreover, the identity equation (16) turns out to be the relation

$$
\begin{equation*}
4 h_{1}^{5} h_{2}+h_{3}^{3}-h_{4}^{2}=0 \tag{17}
\end{equation*}
$$

among $h_{1}, h_{2}, h_{3}, h_{4}$. Following the argument in the previous section, we put

$$
\begin{equation*}
L=-\frac{h_{3}}{h_{1}^{5 / 3}}, \quad M=\frac{h_{4}}{h_{1}^{5 / 2}} . \tag{18}
\end{equation*}
$$

Then (17) turns out to be

$$
\begin{equation*}
-4 h_{2}+L^{3}+M^{2}=0, \tag{19}
\end{equation*}
$$

which is an analogue of (3) and (B3). We introduce vector fields

$$
\begin{equation*}
V=-\frac{1}{20 x_{3}^{5 / 6}}\left(18 x_{2} V_{3}+\left(9 x_{1} x_{2}-10 x_{3}\right) V_{2}\right), \quad W=\frac{1}{2} x_{3}^{-5 / 12}\left(x_{1} V_{2}+2 V_{3}\right) \tag{20}
\end{equation*}
$$

It is easy to check that

$$
V L=M, \quad V M=-\frac{3}{2} L^{2}, \quad W L=W M=0
$$

We put

$$
\left\{\begin{align*}
P(t) & =t^{3}+3 L t+2 M  \tag{21}\\
\varphi & =\left(3 x_{2}^{2}-2 x_{1} x_{3}\right) x_{3}^{-5 / 6}, \\
\tau & =\left(9 x_{1} x_{2}-2 x_{3}\right) x_{3}^{-1 / 4}
\end{align*}\right.
$$

Then it is straightforward to show that (B1)-(B5) hold for $\varphi$ and $\tau$.
Summarizing the above argument, we obtain the following.
THEOREM 5.1. Put $E=x_{1} \partial_{x_{1}}+2 x_{2} \partial_{x_{2}}+3 x_{3} \partial_{x_{3}}$. Then $\{F, L, M, E, V, W, \varphi, \tau\}$ is a uniformizing model of type $A_{3}$, where $F=\operatorname{det}\left(M_{B, 6}\right)$ and $L, M, V, W, \varphi, \tau$ are defined by (18), (20) (21).

As a consequence, we construct a uniformizing model of type $A_{3}$ from the polynomial $f_{0}=\operatorname{det}\left(M_{B, 6}\right)$.

The problem (D2) is the next one to solve. It is equivalent to solve

$$
\begin{equation*}
\varphi=\wp\left(\eta, u_{1}, u_{2}\right), \quad 2 \tau=\wp^{\prime}\left(\eta, u_{1}, u_{2}\right), \quad-12 L=g_{2}, \tag{22}
\end{equation*}
$$

which is a system of algebraic equations for $x_{1}, x_{2}, x_{3}$ (cf. (14)).
In the rest of this subsection, we study (22) in detail. We first introduce $y_{1}, y_{2}, y_{3}$ by

$$
\begin{equation*}
y_{1}=x_{1} / x_{3}^{5 / 24}, \quad y_{2}=x_{2} / x_{3}^{5 / 12}, \quad y_{3}=x_{3}^{3 / 8} . \tag{23}
\end{equation*}
$$

These imply

$$
\begin{equation*}
x_{1}=y_{1} y_{3}^{5 / 9}, \quad x_{2}=y_{2} y_{3}^{10 / 9}, \quad x_{3}=y_{3} y_{3}^{5 / 3}=y_{3}^{8 / 3} . \tag{24}
\end{equation*}
$$

Then we have

$$
\left\{\begin{array}{l}
\varphi=3 y_{2}^{2}-2 y_{1} y_{3}  \tag{25}\\
\tau=y_{3}\left(9 y_{1} y_{2}-2 y_{3}\right) \\
L=-\left(9 y_{2}^{4}+6 y_{1} y_{2}^{2} y_{3}+y_{1}^{2} y_{3}^{2}-4 y_{2} y_{3}^{2}\right)
\end{array}\right.
$$

Noting (22) and (25), we introduce the system of algebraic equations for $y_{1}, y_{2}, y_{3}$
by

$$
\left\{\begin{array}{l}
3 y_{2}^{2}-2 y_{1} y_{3}-X=0  \tag{26}\\
2 y_{3}\left(9 y_{1} y_{2}-2 y_{3}\right)-Y=0 \\
12\left(9 y_{2}^{4}+6 y_{1} y_{2}^{2} y_{3}+y_{1}^{2} y_{3}^{2}-4 y_{2} y_{3}^{2}\right)-g_{2}=0
\end{array}\right.
$$

Note that $X, Y, g_{2}$ are constants but these come from elliptic curve

$$
Y^{2}=4 X^{3}-g_{2} X-g_{3} .
$$

For a moment, $g_{3}$ is regarded as the constant defined by $g_{3}=4 X^{3}-g_{2} X-Y^{2}$. From the first equation of (26), it follows that

$$
\begin{equation*}
y_{1}=\frac{3 y_{2}^{2}-X}{2 y_{3}} . \tag{27}
\end{equation*}
$$

Then the second and third equations of (26) are reduced to

$$
\left\{\begin{array}{l}
Y+9 X y_{2}-27 y_{2}^{3}+4 y_{3}^{2}=0  \tag{28}\\
g_{2}-3 X^{2}+54 X y_{2}^{2}-243 y_{2}^{4}+48 y_{2} y_{3}^{2}=0
\end{array}\right.
$$

To solve (28), we recall some basic properties of elliptic functions. We first factorize

$$
4 X^{3}-g_{2} X-g_{3}=4\left(X-e_{1}\right)\left(X-e_{2}\right)\left(X-e_{3}\right)
$$

and introduce $q_{1}, q_{2}, q_{3}$ by $q_{j}=\sqrt{X-e_{j}} \quad(j=1,2,3)$. (Usually $q_{j}$ is denoted by $\sigma_{j} / \sigma$ in the elliptic function theory.) Then

$$
Y^{2}=4\left(X-e_{1}\right)\left(X-e_{2}\right)\left(X-e_{3}\right)=4 q_{1}^{2} q_{2}^{2} q_{3}^{2} .
$$

Noting this, we assume that $Y=-2 q_{1} q_{2} q_{3}$. Since $X=e_{j}+q_{j}^{2}$, and $e_{1}+e_{2}+e_{3}=0$, it follows that $X=\frac{q_{1}^{2}+q_{2}^{2}+q_{3}^{2}}{3}$. As a consequence

$$
g_{2}=-\frac{4}{3}\left(q_{1}^{2} q_{2}^{2}+q_{1}^{2} q_{3}^{2}+q_{2}^{2} q_{3}^{2}-q_{1}^{4}-q_{2}^{4}-q_{3}^{4}\right)
$$

Eliminating the terms of equations in (26) containing $y_{3}^{2}$, we obtain

$$
\begin{equation*}
81 y_{2}^{4}-54 X y_{2}^{2}-12 Y y_{2}+g_{2}-3 X^{2}=0 \tag{29}
\end{equation*}
$$

which is regarded as an algebraic equation for $y_{2}$. Since

$$
\begin{aligned}
& 81 y_{2}^{4}-54 X y_{2}^{2}-12 Y y_{2}+g_{2}-3 X^{2} \\
= & 81\left(y_{2}^{2}+\frac{2}{3} q_{1} y_{2}-\frac{1}{9}\left(X+2 e_{1}\right)+\frac{1}{9 q_{1}} Y\right)\left(y_{2}^{2}-\frac{2}{3} q_{1} y_{2}-\frac{1}{9}\left(X+2 e_{1}\right)-\frac{1}{9 q_{1}} Y\right) \\
= & 81\left(y_{2}+\frac{q_{1}+q_{2}+q_{3}}{3}\right)\left(y_{2}+\frac{q_{1}-q_{2}-q_{3}}{3}\right) \\
& \times\left(y_{2}+\frac{-q_{1}+q_{2}-q_{3}}{3}\right)\left(y_{2}+\frac{-q_{1}-q_{2}+q_{3}}{3}\right),
\end{aligned}
$$

it is easy to solve (29). As a consequence,

$$
\begin{equation*}
y_{2}=-\frac{q_{1}+q_{2}+q_{3}}{3} \tag{30}
\end{equation*}
$$

is one of solutions to (29). Assuming that $y_{2}$ is given by (30), we have

$$
\left\{\begin{array}{l}
y_{3}^{2}=-\frac{\left(q_{2}+q_{3}\right)\left(q_{3}+q_{1}\right)\left(q_{1}+q_{2}\right)}{2}  \tag{31}\\
y_{1}=\frac{q_{2} q_{3}+q_{3} q_{1}+q_{1} q_{2}}{3 y_{3}}
\end{array}\right.
$$

Finally, taking

$$
U=-\frac{\left(q_{2}+q_{3}\right)\left(q_{3}+q_{1}\right)\left(q_{1}+q_{2}\right)}{2}
$$

we obtain

$$
\left\{\begin{array}{l}
x_{1}=\frac{q_{2} q_{3}+q_{3} q_{1}+q_{1} q_{2}}{3} \cdot U^{-2 / 9}  \tag{32}\\
x_{2}=-\frac{q_{1}+q_{2}+q_{3}}{3} \cdot U^{5 / 9} \\
x_{3}=U^{4 / 3}
\end{array}\right.
$$

Concerning $h_{2}, h_{3}, h_{4}, \varphi, \tau$, we have

$$
\begin{aligned}
& h_{2}=-\frac{1}{432}\left(q_{2}^{2}-q_{3}^{2}\right)^{2}\left(q_{3}^{2}-q_{1}^{2}\right)^{2}\left(q_{1}^{2}-q_{2}^{2}\right)^{2} \\
& h_{3}=\frac{1}{9}\left(q_{1}^{4}+q_{2}^{4}+q_{3}^{4}-q_{2}^{2} q_{3}^{2}-q_{3}^{2} q_{1}^{2}-q_{1}^{2} q_{2}^{2}\right) U^{20 / 9} \\
& h_{4}=-\frac{1}{54}\left(-2 q_{1}^{2}+q_{2}^{2}+q_{3}^{2}\right)\left(q_{1}^{2}-2 q_{2}^{2}+q_{3}^{2}\right)\left(q_{1}^{2}+q_{2}^{2}-2 q_{3}^{2}\right) U^{10 / 3}
\end{aligned}
$$

$$
\begin{aligned}
\varphi & =\frac{1}{3}\left(q_{1}^{2}+q_{2}^{2}+q_{3}^{2}\right) \\
\tau & =-q_{1} q_{2} q_{3}
\end{aligned}
$$

### 5.2. Example 2: The discriminant of the real reflection group of type $\boldsymbol{H}_{3}$

Let $F_{12}, G_{12}, P_{12}$ be the polynomials of $x, s$ introduced in $[9$, p.5]:

$$
\begin{aligned}
F_{12}= & x^{4}-4(s+3) x^{3}+\left(s^{2}+6 s+14\right) x^{2}+2(s+6) x+1, \\
G_{12}= & s x^{3}-4\left(s^{2}+3 s-1\right) x^{2}-4(2 s+11) x-4 \\
P_{12}= & 2 x^{6}-12(s+3) x^{5}+15\left(s^{2}+6 s+10\right) x^{4}+2 s\left(s^{2}+9 s+15\right) x^{3} \\
& +6\left(s^{2}+9 s+25\right) x^{2}+6(s+6) x+2
\end{aligned}
$$

We also introduce the map $\zeta_{12}(x, s)=\frac{27(s+4)^{3}}{4} \cdot \frac{x^{5} G_{12}}{F_{12}^{3}}$ which coincides with $1 / \varphi_{12}$ in [9]. It is easy to check that

$$
\begin{equation*}
4 F_{12}^{3}-27(s+4)^{3} x^{5} G_{12}-P_{12}^{2}=0 \tag{33}
\end{equation*}
$$

We introduce $\tilde{x}, \tilde{s}$ by $\tilde{x}=\frac{2 x_{2}^{2}+x_{1} x_{3}}{\left(x_{1}^{3}-2 x_{2}\right) x_{2}}, \tilde{s}=\frac{2\left(x_{1}^{3}-2 x_{2}\right)}{x_{2}}$, which are rational functions of $x_{1}, x_{2}, x_{3}$. We write $\zeta_{12}(\tilde{x}, \tilde{s})$ by $x_{1}, x_{2}, x_{3}$. For this purpose, we introduce weighted homogeneous polynomials of type $(1,3,5)$ by

$$
\begin{aligned}
h_{1 a}= & x_{1}^{3}-2 x_{2}, \\
h_{1 b}= & 2 x_{2}^{2}+x_{1} x_{3}, \\
h_{1}= & h_{1 a} h_{1 b}, \\
h_{2}= & 50 x_{1}^{3} x_{2}^{4}-108 x_{2}^{5}+40 x_{1}^{4} x_{2}^{2} x_{3}-90 x_{1} x_{2}^{3} x_{3}+8 x_{1}^{5} x_{3}^{2}-20 x_{1}^{2} x_{2} x_{3}^{2}-x_{3}^{3}, \\
h_{3}= & 25 x_{1}^{8} x_{2}^{4}-128 x_{1}^{5} x_{2}^{5}+160 x_{1}^{2} x_{2}^{6}+20 x_{1}^{9} x_{2}^{2} x_{3}-100 x_{1}^{6} x_{2}^{3} x_{3}+80 x_{1}^{3} x_{2}^{4} x_{3} \\
& +96 x_{2}^{5} x_{3}+4 x_{1}^{10} x_{3}^{2}-20 x_{1}^{7} x_{2} x_{3}^{2}-10 x_{1}^{4} x_{2}^{2} x_{3}^{2}+80 x_{1} x_{2}^{3} x_{3}^{2}-8 x_{1}^{5} x_{3}^{3} \\
& +20 x_{1}^{2} x_{2} x_{3}^{3}+x_{3}^{4}, \\
h_{4}= & 125 x_{1}^{12} x_{2}^{6}-960 x_{1}^{9} x_{2}^{7}+3120 x_{1}^{6} x_{2}^{8}-5120 x_{1}^{3} x_{2}^{9}+3456 x_{2}^{10}+150 x_{1}^{13} x_{2}^{4} x_{3} \\
& -1134 x_{1}^{10} x_{2}^{5} x_{3}+3960 x_{1}^{7} x_{2}^{6} x_{3}-7440 x_{1}^{4} x_{2}^{7} x_{3}+5760 x_{1} x_{2}^{8} x_{3}+60 x_{1}^{14} x_{2}^{2} x_{3}^{2} \\
& -450 x_{1}^{11} x_{2}^{3} x_{3}^{2}+1875 x_{1}^{8} x_{2}^{4} x_{3}^{2}-4440 x_{1}^{5} x_{2}^{5} x_{3}^{2}+4080 x_{1}^{2} x_{2}^{6} x_{3}^{2}+8 x_{1}^{15} x_{3}^{3} \\
& -60 x_{1}^{12} x_{2} x_{3}^{3}+390 x_{1}^{9} x_{2}^{2} x_{3}^{3}-1280 x_{1}^{6} x_{2}^{3} x_{3}^{3}+1320 x_{1}^{3} x_{2}^{4} x_{3}^{3}+144 x_{2}^{5} x_{3}^{3}+30 x_{1}^{10} x_{3}^{4}
\end{aligned}
$$

$$
-150 x_{1}^{7} x_{2} x_{3}^{4}+135 x_{1}^{4} x_{2}^{2} x_{3}^{4}+120 x_{1} x_{2}^{3} x_{3}^{4}-12 x_{1}^{5} x_{3}^{5}+30 x_{1}^{2} x_{2} x_{3}^{5}+x_{3}^{6} .
$$

Then $\zeta_{12}(\tilde{x}, \tilde{s})=-\frac{108 h_{1}^{5} h_{2}}{h_{3}^{3}}$. It is easy to show that

$$
\begin{equation*}
108 h_{1}^{5} h_{2}+h_{3}^{3}-h_{4}^{2}=0, \tag{34}
\end{equation*}
$$

which is equivalent to the relation (33). As a consequence, we have

$$
1-\zeta_{12}(\tilde{x}, \tilde{s})=\frac{h_{4}^{2}}{h_{3}^{3}} .
$$

In this case, $h_{2}$ is regarded as the discriminant of the reflection group of type $H_{3}$. In particular $h_{2}=0$ is a free divisor in the ( $x_{1}, x_{2}, x_{3}$ )-space. To show this, we introduce a matrix $M_{H_{3}}$ by

$$
M_{H_{3}}=\left(\begin{array}{ccc}
x_{1} & 3 x_{2} & 5 x_{3} \\
\frac{2}{3}\left(4 x_{1}^{3}-9 x_{2}\right), & x_{3} & -\frac{10}{3} x_{1}\left(3 x_{2}^{2}+2 x_{1} x_{3}\right) \\
\frac{1}{3}\left(-16 x_{1}^{5}+40 x_{1}^{2} x_{2}+3 x_{3}\right) & 5 x_{1} x_{2}^{2} & \frac{10}{3}\left(6 x_{1}^{3} x_{2}^{2}-9 x_{2}^{3}+4 x_{1}^{4} x_{3}-4 x_{1} x_{2} x_{3}\right)
\end{array}\right)
$$

and define vector fields $V_{j}(j=1,2,3)$ by

$$
{ }^{t}\left(V_{1}, V_{2}, V_{3}\right)=M_{H_{3}}{ }^{t}\left(\partial_{x_{1}}, \partial_{x_{2}}, \partial_{x_{3}}\right) .
$$

Then

$$
\operatorname{det}\left(M_{H_{3}}\right)=5 h_{2}, \quad V_{1} h_{2}=15 h_{2}, \quad V_{2} h_{2}=0, \quad V_{3} h_{2}=0,
$$

which actually show that $h_{2}$ coincides with $\operatorname{det}\left(M_{H_{3}}\right)$ up to a constant factor and that $h_{2}=0$ defines a free divisor. Putting $Z=\zeta_{12}(\tilde{x}, \tilde{s})$, we have

$$
V_{2} Z=-10 x_{1} \cdot \frac{h_{4}}{h_{1} h_{3}} \cdot Z, \quad V_{3} Z=10\left(2 x_{1}^{3}-x_{2}\right) \cdot \frac{h_{4}}{h_{1} h_{3}} \cdot Z .
$$

Noting these equations, we define $V_{3}^{\prime}=V_{3}+\frac{2 x_{1}^{3}-x_{2}}{x_{1}} V_{2}$. Then $V_{3}^{\prime} Z=0$. Moreover, we have

$$
V_{3}^{\prime} h_{1}=-4 x_{1} x_{2} h_{1}, \quad V_{3}^{\prime} h_{3}=-\frac{20}{3} x_{1} x_{2} h_{3}, \quad V_{3}^{\prime} h_{4}=-10 x_{1} x_{2} h_{4},
$$

In this case, we define

$$
\begin{equation*}
L=-\frac{h_{3}}{h_{1}^{5 / 3}}, \quad M=\cdot \frac{h_{4}}{h_{1}^{5 / 2}} . \tag{35}
\end{equation*}
$$

Then it follows that

$$
\begin{equation*}
108 h_{2}=L^{3}+M^{2} \tag{36}
\end{equation*}
$$

We put

$$
\begin{equation*}
V=-\frac{3}{20 h_{1}^{5 / 6}}\left\{3 x_{2}\left(2 x_{1}^{5}-5 x_{1}^{2} x_{2}-x_{3}\right) V_{2}+\left(3 x_{1}^{3} x_{2}-8 x_{2}^{2}-x_{1} x_{3}\right) V_{3}\right\} \tag{37}
\end{equation*}
$$

Then $V L=M, V M=-\frac{3}{2} L^{2}$. Noting these, we introduce a polynomial of $t$ by $P(t)=t^{3}+3 L t+2 M$. We are going to find functions $\varphi=\varphi\left(x_{1}, x_{2}, x_{3}\right)$ and $\tau=\tau\left(x_{1}, x_{2}, x_{3}\right)$ such that $P(\varphi)=\tau^{2}$. After a little tedious computation, we find that

$$
\begin{equation*}
\varphi=\frac{\varphi_{0}}{h_{1}^{5 / 6}} \tag{38}
\end{equation*}
$$

where

$$
\varphi_{0}=-7 x_{1}^{4} x_{2}^{2}+16 x_{1} x_{2}^{3}-4 x_{1}^{5} x_{3}+10 x_{1}^{2} x_{2} x_{3}+x_{3}^{2} .
$$

Then

$$
P(\varphi)=\frac{108 x_{2}^{2} h_{1 a}^{2}}{h_{1}^{1 / 2}}
$$

Moreover we put

$$
\begin{equation*}
W=\frac{\sqrt{3}}{2} \cdot \frac{1}{h_{1}^{5 / 12}} \cdot\left(\left(2 x_{1}^{3}-x_{2}\right) V_{2}+x_{1} V_{3}\right) \tag{39}
\end{equation*}
$$

Then

$$
W \varphi=\frac{6 \sqrt{3} x_{2} h_{1 a}}{h_{1}^{1 / 4}} .
$$

These identities imply that

$$
P(\varphi)=(W \varphi)^{2} .
$$

On the other hand, it is easy to show that

$$
W L=W M=0 .
$$

Comparing the argument above with that in the previous section, we define

$$
\tau_{0}=6 \cdot 3^{1 / 2} x_{2} h_{1 a}
$$

and

$$
\begin{equation*}
\tau=\frac{\tau_{0}}{h_{1}^{1 / 4}} \tag{40}
\end{equation*}
$$

Then

$$
P(\varphi)=\tau^{2}, \quad W \varphi=\tau
$$

Moreover, by direct computation, we find that (B1)-(B5) hold.
Theorem 5.2. Put $E=x_{1} \partial_{x_{1}}+3 x_{2} \partial_{x_{2}}+5 x_{3} \partial_{x_{3}}$. Then $\{F, L, M, E, V, W, \varphi, \tau\}$ is a uniformizing model of type $A_{3}$, where $F=h_{2}$ and $L, M, V, W, \varphi, \tau$ are defined by (35), (37), (39), (38), (40).

The proof of this theorem is a consequence of the argument above.
We have thus constructed a uniformizing model of type $A_{3}$ from the discriminant of the reflection group of type $H_{3}$. The problem to be done is to solve

$$
\varphi=y_{1}, \quad 2 \tau=y_{2}, \quad-12 L=y_{3},
$$

which is a system of algebraic equations for $x_{1}, x_{2}, x_{3}$, where $y_{1}, y_{2}, y_{3}$ are constants (cf. (22)). This problem is not solved in the present paper and left to the future study.

### 5.3. Example 3: The almost Belyi function constructed by A. V. Kitaev

We treat one of the almost Belyi functions constructed by Kitaev [2]. We define a function $z$ of $z_{1}$ and $s$ by

$$
\begin{equation*}
z=-\frac{2^{5} 3^{3}\left(s^{2}-5\right)^{5}}{(s+3)^{9}(s-2)^{6}} \cdot \frac{\left(z_{1}-a\right)^{5}\left(z_{1}-1\right)^{2} z_{1}\left(z_{1}-t\right)}{\left(z_{1}^{4}+c_{3} z_{1}^{3}+c_{2} z_{1}^{2}+c_{1} z_{1}+c_{0}\right)^{3}}, \tag{41}
\end{equation*}
$$

where

$$
\begin{aligned}
& a=\frac{(s-1)\left(s^{2}-5\right)}{2^{3}(s-2)^{2}} \\
& t=\frac{2 s^{3}\left(s^{2}-5\right)}{(s-2)^{2}(s+3)^{3}} \\
& c_{0}=\frac{s^{2}\left(s^{2}-5\right)^{4}}{2^{4}(s+3)^{4}(s-2)^{6}} \\
& c_{1}=-\frac{\left(-5+s^{2}\right)^{3}\left(45-75 s+65 s^{2}-35 s^{3}+8 s^{4}\right)}{4(-2+s)^{6}(3+s)^{4}} \\
& c_{2}=\frac{5(-1+s)\left(-5+s^{2}\right)^{2}\left(-9-3 s+2 s^{2}+2 s^{3}\right)}{2(-2+s)^{4}(3+s)^{4}} \\
& c_{3}=-\frac{2\left(s^{2}-5\right)\left(2 s^{3}+5 s^{2}-15\right)}{(s+3)^{3}(s-2)^{2}}
\end{aligned}
$$

By definition, $z$ is an almost Belyi function.
We introduce a free divisor defined by the matrix $M_{E_{13}}$ below:

$$
M_{E_{13}}=\left(\begin{array}{ccc}
x_{1} & 2 x_{2} & 5 x_{3} \\
m_{21} & m_{22} & m_{23} \\
m_{31} & m_{32} & m_{33}
\end{array}\right)
$$

where

$$
\begin{aligned}
& m_{21}=-2\left(36 x_{1}^{4}+31 x_{1}^{2} x_{2}+6 x_{2}^{2}\right), \\
& m_{22}=36 x_{1}^{3} x_{2}+8 x_{1} x_{2}^{2}+3 x_{3}, \\
& m_{23}=20 x_{1}\left(9 x_{1}^{2}+4 x_{2}\right) x_{3}, \\
& m_{31}=-432 x_{1}^{5}-396 x_{1}^{3} x_{2}-88 x_{1} x_{2}^{2}+3 x_{3}, \\
& m_{32}=-4 x_{2}\left(-54 x_{1}^{4}-15 x_{1}^{2} x_{2}+2 x_{2}^{2}\right), \\
& m_{33}=20\left(54 x_{1}^{4}+27 x_{1}^{2} x_{2}+2 x_{2}^{2}\right) x_{3} .
\end{aligned}
$$

Let $V_{1}, V_{2}, V_{3}$ be the vector fields defined by $M_{E_{13}}$ as before. Putting $f_{0}=$ $\operatorname{det}\left(M_{E_{13}}\right)$, we find that

$$
V_{1} f_{0}=15 f_{0}, \quad V_{2} f_{0}=V_{3} f_{0}=0
$$

This shows that $f_{0}=0$ is a free divisor.
Remark 5.3. We remark on the polynomial $f_{0}$ introduced in this subsection. If $x_{1}=0$, then $f_{0}$ turns out to be $x_{3}\left(x_{3}^{2}-32 x_{2}^{5}\right)$ up to a constant factor. This implies that if $x_{1}=0$, the curve defined by $f_{0}=0$ has the $E_{13}$-singularity in the sense of Arnol'd. Moreover, regarding $x_{1}$ as a parameter, $f_{0}=0$ defines a family of curves in the ( $x_{2}, x_{3}$ )-plane which is a deformation of the $E_{13}$-singularity. The polynomial $f_{0}$ coincides with the polynomial introduced in [1, §7.1].

To rewrite the almost Belyi function $z$ defined above in terms of the coordinate
$\left(x_{1}, x_{2}, x_{3}\right)$, we introduce polynomials $h_{1 a}, h_{1 b}, h_{1}, h_{2}, h_{3}, h_{4}$ by

$$
\begin{aligned}
h_{1 a}= & 2 x_{1}^{2}+x_{2}, \\
h_{1 b}= & x_{2}^{3}+x_{1} x_{3}, \\
h_{1}= & h_{1 a} h_{1 b}, \\
h_{2}= & -200 x_{1}^{4} x_{2}^{3}-160 x_{1}^{2} x_{2}^{4}-32 x_{2}^{5}-216 x_{1}^{5} x_{3}-180 x_{1}^{3} x_{2} x_{3}-40 x_{1} x_{2}^{2} x_{3}+x_{3}^{2}, \\
h_{3}= & 400 x_{1}^{4} x_{2}^{8}+320 x_{1}^{2} x_{2}^{9}+64 x_{2}^{10}+1024 x_{1}^{5} x_{2}^{5} x_{3}+800 x_{1}^{3} x_{2}^{6} x_{3}+160 x_{1} x_{2}^{7} x_{3} \\
& +640 x_{1}^{6} x_{2}^{2} x_{3}^{2}+320 x_{1}^{4} x_{2}^{3} x_{3}^{2} \\
& -40 x_{1}^{2} x_{2}^{4} x_{3}^{2}-32 x_{2}^{5} x_{3}^{2}-192 x_{1}^{5} x_{3}^{3}-160 x_{1}^{3} x_{2} x_{3}^{3}-40 x_{1} x_{2}^{2} x_{3}^{3}+x_{3}^{4}, \\
h_{4}= & 8000 x_{1}^{6} x_{2}^{12}+9600 x_{1}^{4} x_{2}^{13}+3840 x_{1}^{2} x_{2}^{14}+512 x_{2}^{15}+30720 x_{1}^{7} x_{2}^{9} x_{3} \\
& +36288 x_{1}^{5} x_{2}^{10} x_{3}+14400 x_{1}^{3} x_{2}^{11} x_{3}+1920 x_{1} x_{2}^{12} x_{3}+49920 x_{1}^{8} x_{2}^{6} x_{3}^{2} \\
& +63360 x_{1}^{6} x_{2}^{7} x_{3}^{2}+30000 x_{1}^{4} x_{2}^{8} x_{3}^{2}+6240 x_{1}^{2} x_{2}^{x_{2} x_{3}^{2}+480 x_{2}^{10} x_{3}^{2}+40960 x_{1}^{9} x_{2}^{3} x_{3}^{3}} \\
& +59520 x_{1}^{7} x_{2}^{4} x_{3}^{3}+35520 x_{1}^{5} x_{2}^{5} x_{3}^{3}+10240 x_{1}^{3} x_{2}^{6} x_{3}^{3}+1200 x_{1} x_{2}^{7} x_{3}^{3}+13824 x_{1}^{10} x_{3}^{4} \\
& +23040 x_{1}^{8} x_{2} x_{3}^{4}+16320 x_{1}^{6} x_{2}^{2} x_{3}^{4}+5280 x_{1}^{4} x_{2}^{3} x_{3}^{4}+540 x_{1}^{2} x_{2}^{4} x_{3}^{4}-48 x_{2}^{5} x_{3}^{4} \\
& -288 x_{1}^{5} x_{3}^{5}-240 x_{1}^{3} x_{2} x_{3}^{5}-60 x_{1} x_{2}^{2} x_{3}^{5}+x_{3}^{6} .
\end{aligned}
$$

Note that $x_{3} h_{2}$ coincides with $f_{0}$ up to a constant factor. By direct computation, we find that

$$
\begin{equation*}
2^{10} \cdot 3^{3} h_{1}^{5} x_{3}^{2} h_{2}-h_{3}^{3}+h_{4}^{2}=0 \tag{42}
\end{equation*}
$$

Then $Z=\frac{2^{10} \cdot 3^{3} h_{1}^{5} x_{3}^{2} h_{2}}{h_{3}^{3}}$ is the almost Belyi function essentially the same as $z$ introduced in (41). In particular, (42) shows that $Z-1=-\frac{h_{4}^{2}}{h_{3}^{3}}$. This reflects an important property of the almost Belyi function.

We define vector field $V, W$ by

$$
\left\{\begin{array}{c}
V=\frac{1}{10 x_{3}^{1 / 6} h_{1}^{5 / 6}\left\{\left(-36 x_{1}^{3} x_{2}^{2}-14 x_{1} x_{2}^{3}-2 x_{1}^{2} x_{3}+x_{2} x_{3}\right) V_{2}\right.}  \tag{43}\\
\left.\quad+\left(6 x_{1}^{2} x_{2}^{2}+2 x_{2}^{3}+x_{1} x_{3}\right) V_{3}\right\} \\
W=
\end{array}\right.
$$

and functions $L, M$ by

$$
\begin{equation*}
L=-\frac{h_{3}}{x_{3}^{1 / 3} h_{1}^{5 / 3}}, \quad M=\frac{h_{4}}{x_{3}^{1 / 2} h_{1}^{5 / 2}} \tag{44}
\end{equation*}
$$

It is easy to see that

$$
V L=M, \quad V M=-\frac{3}{2} L^{2}, \quad W L=W M=0 .
$$

We put

$$
\left\{\begin{align*}
P(t) & =t^{3}+3 L t+2 M,  \tag{45}\\
\varphi & =\frac{20 x_{1}^{2} x_{2}^{4}+8 x_{2}^{5}-80 x_{1}^{3} x_{2} x_{3}-20 x_{1} x_{2}^{2} x_{3}+x_{3}^{2}}{x_{3}^{1 / 6}\left(h_{0} h_{2}\right)^{5 / 6}}, \\
\tau \quad & =2^{3} \cdot 3^{3 / 2} \cdot x_{3}^{3 / 4} \cdot \frac{-20 x_{1}^{4} x_{2}^{3}-10 x_{1}^{2} x_{2}^{4}-x_{2}^{5}+4 x_{1}^{5} x_{3}}{\left(h_{0} h_{2}\right)^{5 / 4}} .
\end{align*}\right.
$$

Then

$$
P(\varphi)=\tau^{2}, \quad W \varphi=\tau
$$

Theorem 5.4. Put $E=x_{1} \partial_{x_{1}}+2 x_{2} \partial_{x_{2}}+5 x_{3} \partial_{x_{3}}$. Then $\{F, L, M, E, V, W, \varphi, \tau\}$ is a uniformizing model of type $A_{3}$, where $F=\operatorname{det}\left(M_{E_{13}}\right)$ and $L, M, V, W, \varphi, \tau$ are defined by (44), (43), (45).

The proof of this theorem is a consequence of the argument above.
We have thus constructed a uniformizing model of type $A_{3}$ from the polynomial defining the free divisor $f_{0}=0$.

The problem to be done is to solve

$$
\varphi=y_{1}, \quad 2 \tau=y_{2}, \quad-12 L=y_{3},
$$

which is a system of algebraic equations for $x_{1}, x_{2}, x_{3}$, where $y_{1}, y_{2}, y_{3}$ are constants (cf. (22)). This problem is not solved in the present paper and left to the future study.

Acknowledgements. This work was partially supported by JSPS Grant-inAid for Scientific Research No.17K05269.

## References

[1] M. Kato, T. Mano and J. Sekiguchi: Flat structures without potentials. Rev. Roumaine Math. Pures Appl., 60 (2015), 4, 481-505.
[2] A. V. Kitaev, Grothendieck's dessins d'enfants, their deformations and algebraic solutions of the sixth Painlevé and Gauss hypergeometric equations, Algebra i Analiz 17, no. 1 (2005), 224-273.
[3] K. Saito, On the uniformization of complements of discriminant loci. RIMS Kokyuroku 287 (1977), 117-137.
[4] K. Saito: Theory of logarithmic differential forms and logarithmic vector fields. J. Fac. Sci. Univ. Tokyo Sect. IA, Math. 27 (1980) 265-291.
[5] J. Sekiguchi, A classification of weighted homogeneous Saito free divisors in three dimensional space. J. Math. Soc. Japan, 61 (2009), 1071-1095.
[6] J. Sekiguchi, Systems of uniformization equations related with dihedral equations, Kumamoto J. Math. 23 (2010), 7-26.
[7] J. Sekiguchi, Systems of uniformization equations and hyperelliptic integrals, J. Math. Sci. 175 (2011), 57-79.
[8] J. Sekiguchi and R. Vidūnas: Free divisors and almost Belyi functions, in preparation.
[9] R. Vidūnas and A. V. Kitaev, Schlesinger transformations for algebraic Painlevé VI solutions. Zap. Nauchn. Sem. S-Petersburg. Otdel. Mat. Inst. Steklov. (POMI) 433 (2015), 131-154.

## Jiro SEKIGUCHI

Department of Mathematics
Faculty of Engineering
Tokyo University of Agriculture and Technology
Nakacho 2-24-16, Koganei, Tokyo 184-8588, Japan
E-mail: sekiguti@cc.tuat.ac.jp


[^0]:    2010 Mathematics Subject Classification. Primary 14J70; Secondary 34M45, 51F15.
    Key Words and Phrases. Free divisor, uniformization, almost Belyi function.

